



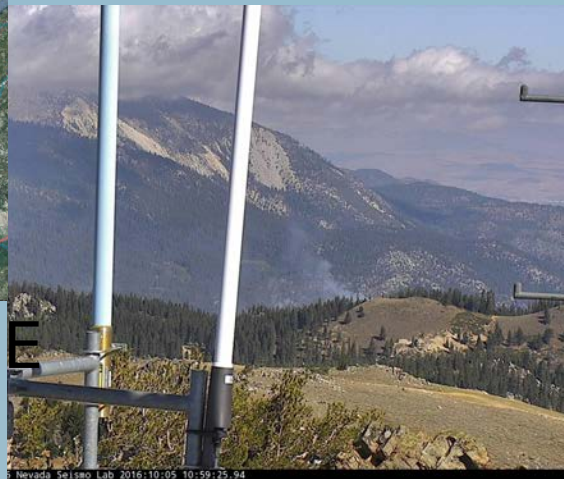
Wildland Fire Intelligence

Carl Pennypacker, Lawrence Berkeley National Lab (LBNL)

Tim Ball, Fireball International

October 16, 2018

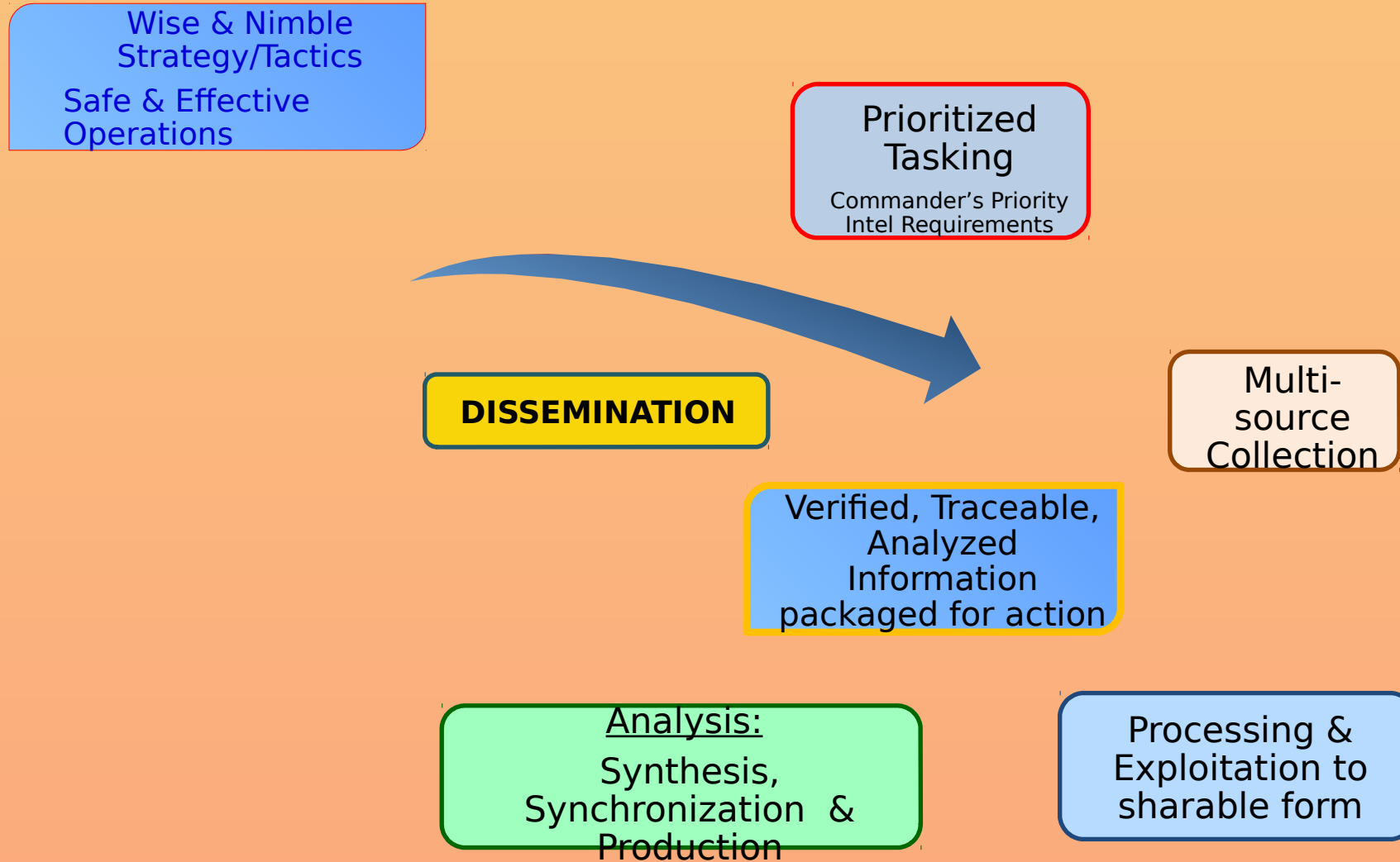
FUEGO



- ACTIONABLE INTELLIGENCE
- EARLY DETECTION
- DEEP LEARNING ANALYSIS (FIRE & FUELS)
- IMPROVED SIMULATION => PRIORITIZATION

The Intelligence Cycle

*Where information is collected and transformed to actionable intelligence
in support of all aspects of operations*



Infamous Fires Fuego Could Have Minimized

Two Examples of Delayed Fire Detection

Corral LAC/CDF Nov 24, 2007
Malibu Bowl

Cause: Bonfire at The Cave at top of Malibu Bowl

Initial Report: 3:29 AM, 100 acres

Weather: 59°F, RH 8%, 27 MPH, G36, Northerly.
RED FLAG conditions. Bonfire detectable so
LACoFD Patrol could have suppressed.

Totals: 4901 Ac, 49 Residence, 31 other structures, 27
Structures Damaged, 10,000 people evacuated



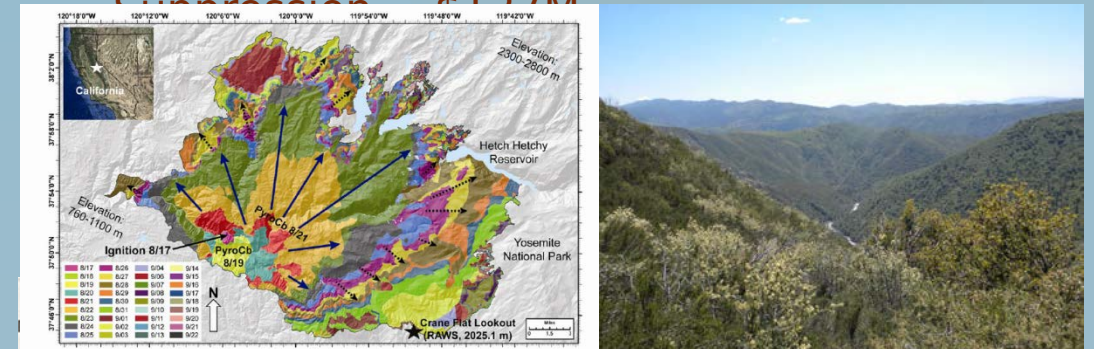
Rim USFS-STF Aug 17, 2013
Tuolumne River Drainage

Cause: Hunter's Cooking Fire

Initial Report: 3:25 PM, Air Tanker Pilot, 40 acres.

Weather: 87°F, RH 17%, 15 MPH, G21, Westerly
Totals: 257,314 Ac, 11 Residence, 98 Outbuildings,
3 Commercial Buildings,

Suppression: \$127M





***Exportable
Wide Area Surveillance with Real Time
Exploitation
Military and Civil Applications***

Shinjuku Cocoon,
Tokyo

Fireball Leadership

J. Timothy Ball
President

B.A. & M.A. Biological Sciences,
Univ. of California, Santa Barbara.
Ph. D. Biological Sciences,
Stanford University.

Experience:
15 Years professor at the Desert
Research Institute.
19 years CEO Fireball

Research:
Linkage of ecosystem and
atmospheric process
through remote
sensing; Fire Ecology
Fire Behavior.



Ryan C. Dotson
Vice President

B.S. Mathematics &
M.S. Applied Mathematics,
University of Nevada, Reno

Experience:
20 years in the software industry
19 years Vice President, COO of
Fireball

Research:
Numerical Modeling,
Statistics, and their
use in Image
Processing and
Navigation

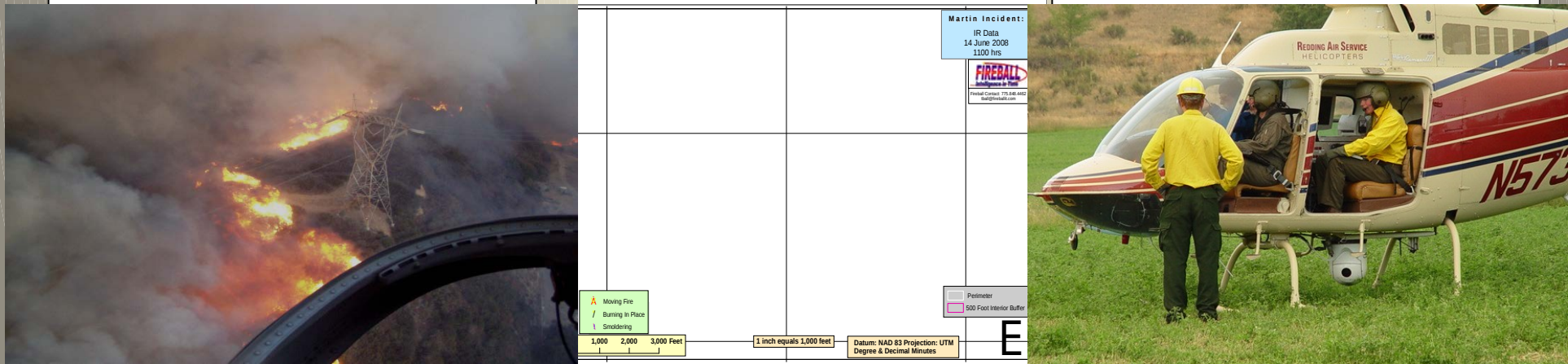


John C. Arvesen
Senior Collaborator

B.S. Engineering Physics, Univ. of
California Berkeley.
M.S. Mechanical Engineering,
Stanford University.

Experience:
35 years at NASA
20 years with NASA U-2/ER-2 High
Altitude Branch.

Long tenure as Branch Chief
included characterization of
atmospheric chemistry in the
Ozone
Hole and
development of
many airborne
sensor systems.



ARGUS Surveillance System on NASA WB-57

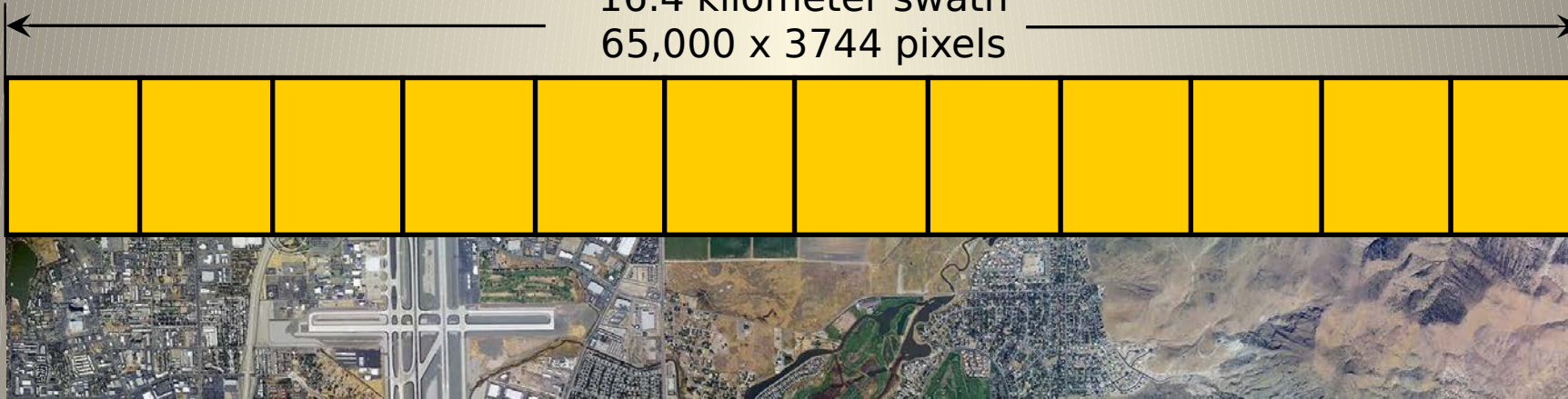


Designed for One Standard WB-57 Pallet



--50,000 feet

59 degree
16.4 kilometer swath
65,000 x 3744 pixels



Standard Configuration (400 mm lenses)

Altitude	System Swath	Nadir GSD	Outer GSD	Ground Speed	Forward Overlap	Side-lap	Frame interval	Max Map Rate	Practical Map Rate	Nominal mapping duration	Area/Flight
15,200 m 50,000 ft	59 deg. 16.4 km	24 cm 9.6 in	37 cm 14.8 in	325 kts	39%	20%	3.3 s	9900 sqkm/hr	6,400 sq. km/hr.	3.25 hours	20,000 sq. km 7,700 sq. mi.
Ultra-wide Configuration (Mix of 400, 200, 100, 85 mm lenses)											
Altitude	System Swath	Nadir GSD	Outer GSD	Ground Speed	Forward Overlap	Side-lap	Frame interval	Max Map Rate	Practical Map Rate	Nominal mapping duration	Area/Flight
15,100 m 50,000 ft	138 deg 18.4 km 11.4 mi	1.2 m 47 in	1.2 m 47 in	350 kts	70%	20%	5 s	23,880 sq.km/hr	15,533 sq km/hr	3.25 hours	50,483 sq. km 19,491 sq. mi.

Argus, Aware® and Tsunami Cooperate

Target Recognition, Localization, and Analysis



Fireball's Argus Large Area High Res Camera



Tsunami Telescope slews to coordinates provided by Argus

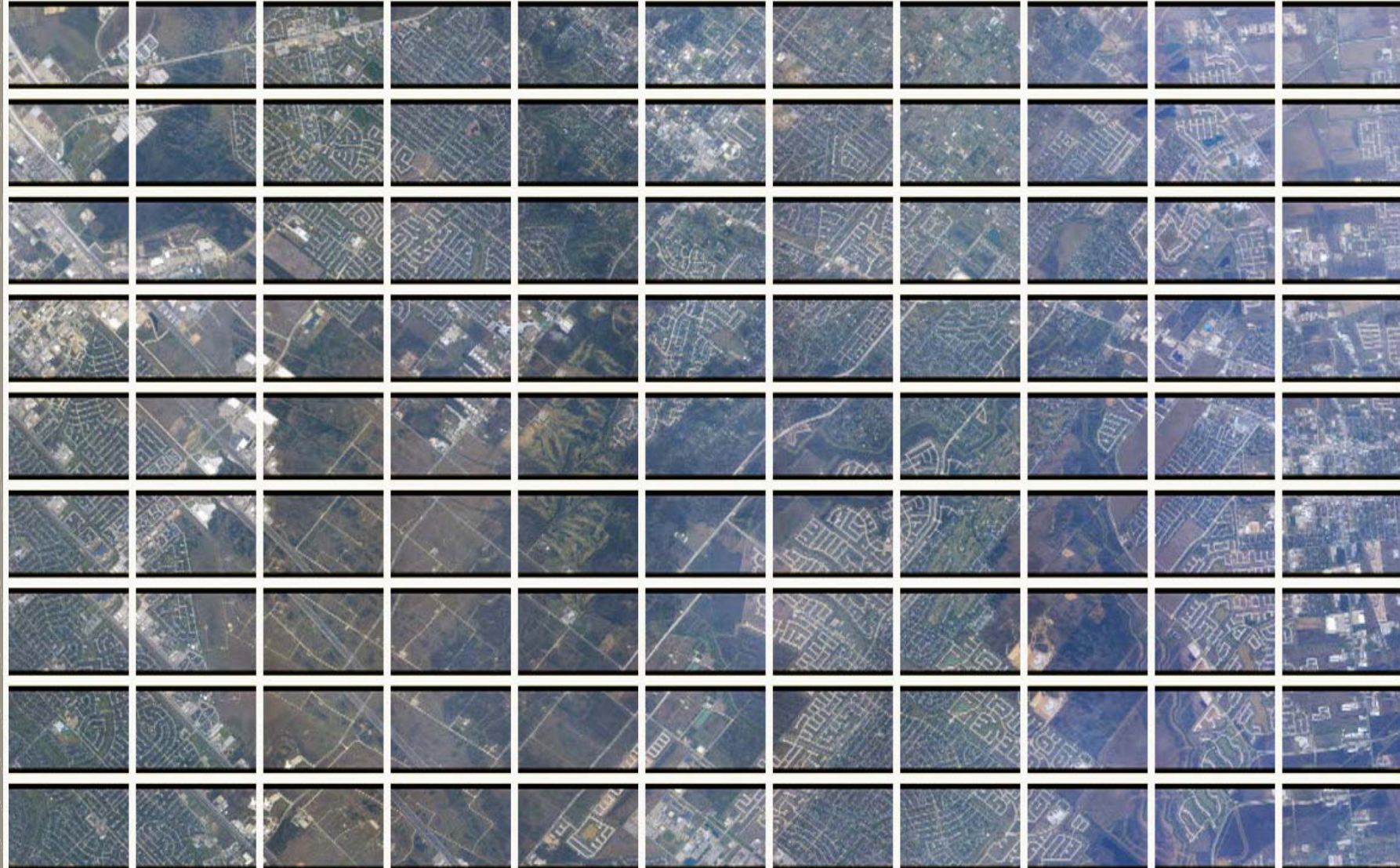
AWARE® Real Time Image Exploitation Software

- ◇ Image "Waterfall" display
- ◇ Image Geo-referenced
- ◇ Image enhanced
- ◇ Full Res display of selected location
- ◇ Image "chipped" to relevant size
- ◇ Image "geo-chip" transmitted off aircraft via multiple networks
- ◇ Target coordinates passed to telescope
- ◇ Recall of image from Database by location or time (for comparison).
- ◇ Geo-Context images transmitted

Telescope Still Frame and Video transmitted via Mil-Star

Argus in Operation:

35 seconds of imagery from 65,000 feet. Houston
12 inch GSD; 9 miles along-track, 13 miles cross-track 75,000 acres





National Soccer Stadium,
Bamako, Mali



The U.S. Forest Service National Infrared Operations (NIROPS) Program: 2016 NIROPs Closeout

November 02, 2016





PHOENIX System Specifications

Two channel thermal IR line scanner, 1680 pixels per scan line

3-5 μm band for intense heat (A channel, mid-wave)

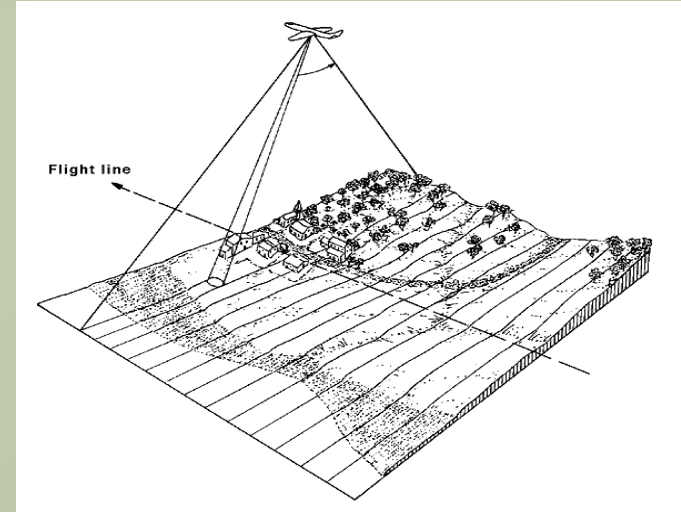
8-12 μm band for background terrain (B channel)

No absolute calibration

Detections from kA-B

k is < 1 and varied by operator to subtract background from the mid-wave.

These two characteristics are among those that forces human interpretation precluding real-time data utilization



Instantaneous Field of View: 1.25 milliradian				Total Field of View: 120 degrees				Cross-track pixels: 1680					
Altitude		Nadir	Nadir	Outer	Outer	Spatial Detection Limit at 1000 degrees F		Night time NADIR		Outer		Swath, km	Swath, miles
	Ft, AGL	GSD, m	GSD, ft	GSD, m	GSD, ft	Sq. cm	Sq. Inches	Sq. cm	Sq. Inches				
Nominal	10,000	3.8	12.5	6.6	21.6	322	50	963	149	10.6	6.6		
Usual	15,000	5.7	18.75	9.9	32.5	724	112	2168	336	15.6	9.9		

GSD = Ground sample Distance, the length of the sides of one pixel projected to the ground; AKA pixel size

NATIONAL **INFRARED** OPERATIONS

Phoenix Spatial Specifications

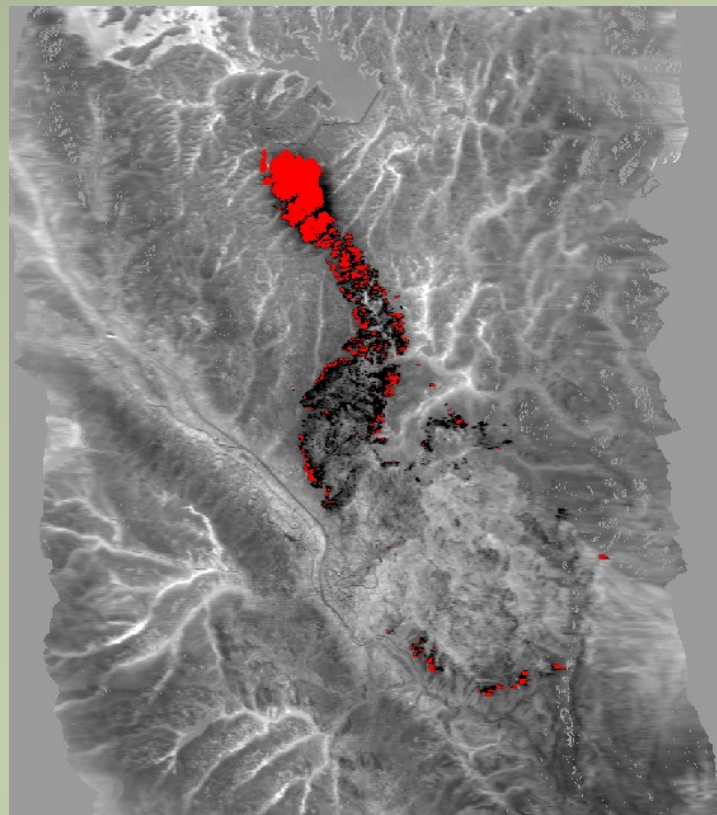
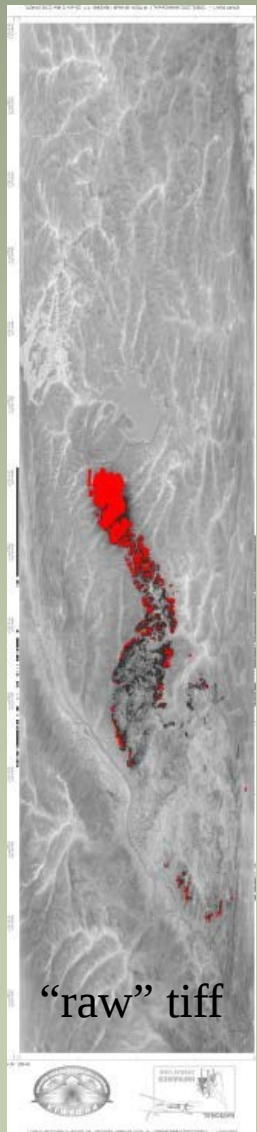


Instantaneous Field of View: 1.25 milliradian					Total Field of View: 120 degrees					Cross-track pixels: 1680			
										Spatial Detection Limit at 1000 degrees F			
Altitude, Ft		Nadir	Nadir		Outer	Outer		Night time NADIR		Outer		Swath, km	Swath, miles
		GSD, m	GSD, ft		GSD, m	GSD, ft		Sq. cm	Sq. Inches	Sq. cm	Sq. Inches		
10,000		3.8	12.5		6.6	21.6		322	50	963	149	10.6	6.6
15,000		5.7	18.75		9.9	32.5		724	112	2168	336	15.6	9.9

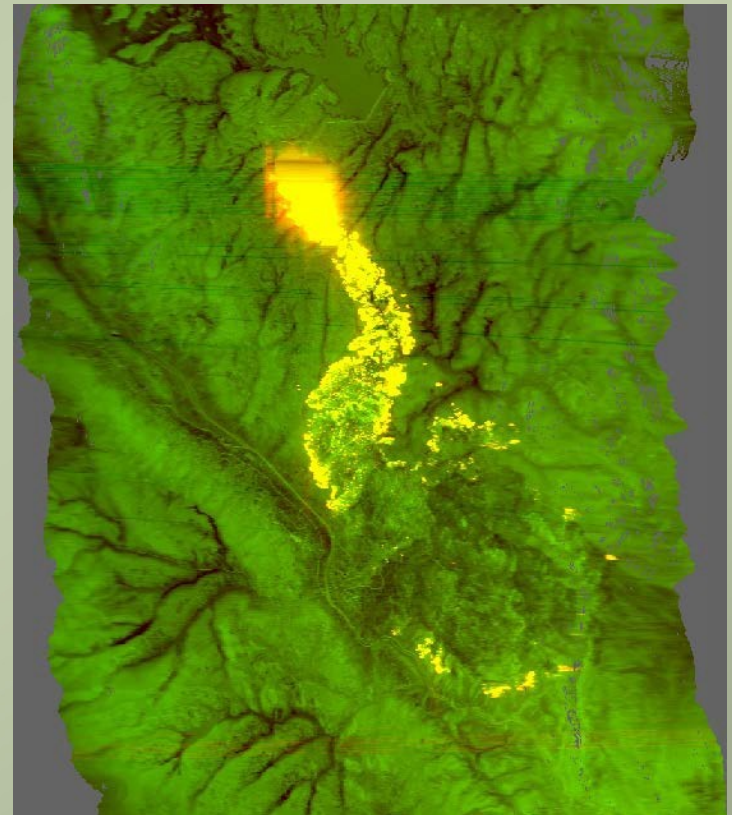
Two Mid-wave Fireball Fire Finder

Instantaneous Field of View: 0.66 milliradian					Total Field of View: 87 degrees					Cross-track pixels: 2300			
										Spatial Detection Limit at 800 degrees F			
Altitude, Ft		Nadir	Nadir		Outer	Outer		Day & Night NADIR		Outer		Swath, km	Swath, miles
		GSD, m	GSD, ft		GSD, m	GSD, ft		Sq. cm	Sq. Inches	Sq. cm	Sq. Inches		
10,000		2	6.6		2.7	8.8		88	13.6	160	25	4.9	3.7
15,000		3	9.8		4.1	13.4		198	30	369	57	7.4	5.2

IR Data delivered from plane



Orthorectified tiff w/ fire detects



Orthorectified color tiff

Waldo Canyon Fire June 25, 2012, 2253 hrs



arcmap - ArcInfo

File Edit View Bookmarks Insert Selection Tools Window Help

Layer: IR Perimeter

Task: CreateNew Feature 3 | Target:

Georeferencing

IR Perimeter
Intense Heat
Scattered Heat
Isolated Heat

110419_0252_PIPELINE_1_ortho.tif
Cooper Mountain
110419_0252_PIPELINE_1_color.tif
Rock House
PKWest
Imagery1_1_MeterRegion_81Texas_NAIP08_4_Bar
Maps\TOPO24k_100k_250k_Lower_48_States

Display Source Selection Stereo 3D Snap

texas_fires.mxd - ArcMap - ArcInfo

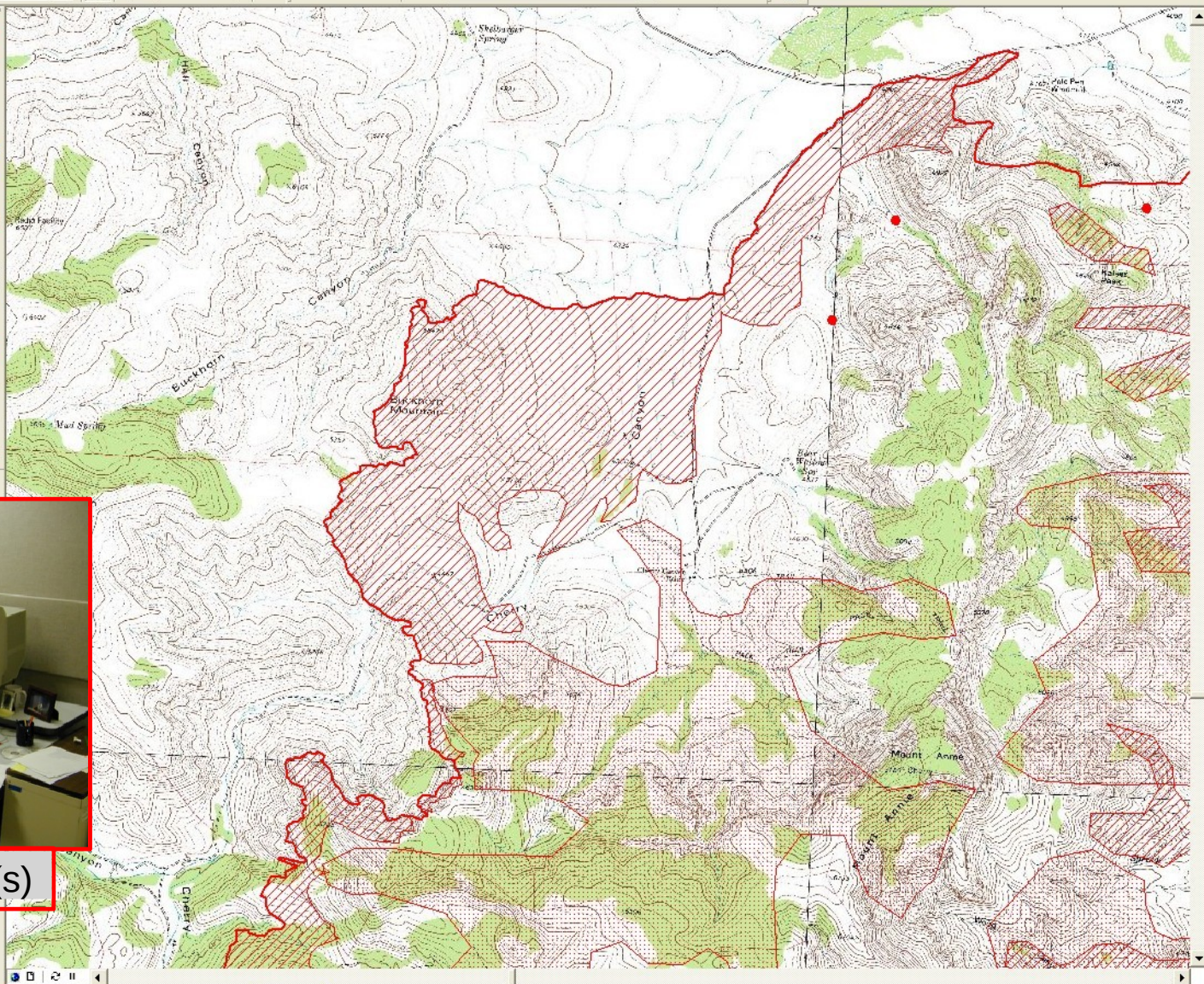
File Edit View Bookmarks Insert Selection Tools Window Help

Editor Task: Create New Feature Target:

1:30.165 Georeferencing Layer:

Layers

- IR Perimeter
- Intense Heat
- Scattered Heat
- Isolated Heat
- 110419_0252_PIPELINE_1_color.tif
- 110419_0252_PIPELINE_1_ortho.tif
- Cooper Mountain
- Wildcat
- Rock House
- PK West
- Imagery\1_Meter\Region_8\Texas_NAIP08_4_Band
- Maps\eTOPO\24k_100k_250k_Lower_48_States



Display Source Selection Stereo 3D Snap

Drawing Arial 10 B I U A

18401.664 3425155.378 Meters

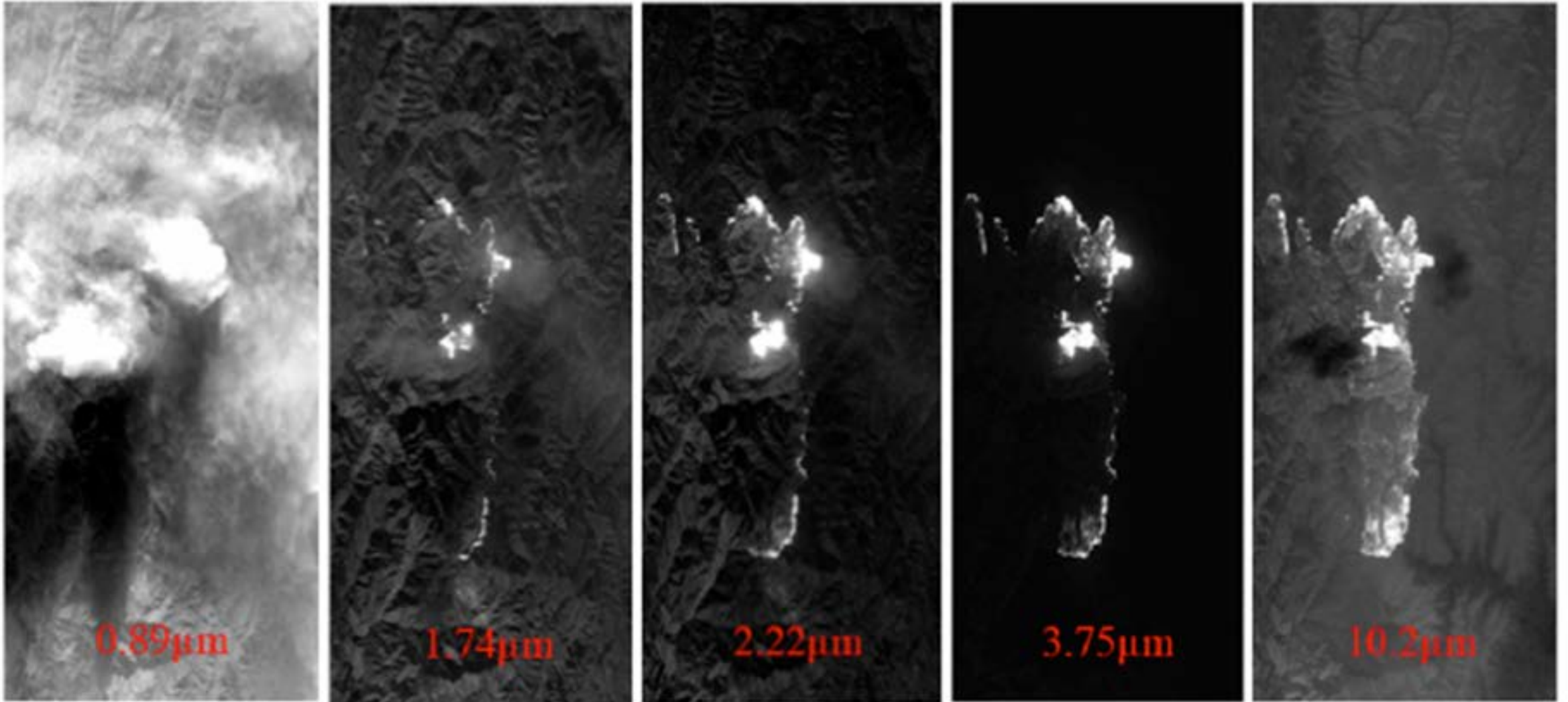


Infrared Interpreter(s)

Some Points To Remember About Phoenix Imagery

- What is captured in the imagery is the relative variation in heat across the fire area
 - No one-to-one correspondence between pixel values and ground temperature
- The technician can adjust the heat “threshold” value during runs across the fire area.
 - Doesn’t allow for automated extraction of heat areas
- There is more heat in the imagery than just the red (DN = 255) pixels!
 - **Requires an Infrared Interpreter (IRIN) to derive products**

These images are from one section of the Zaca Fire in Santa Barbara and Ventura Counties California (2007) taken by the Autonomous Modular Scanner (Built NASA Ames Research Center) flying on the Ikhana (Predator B) Unmanned System demonstrate the different information about a fire that can be understood at different wavelengths.

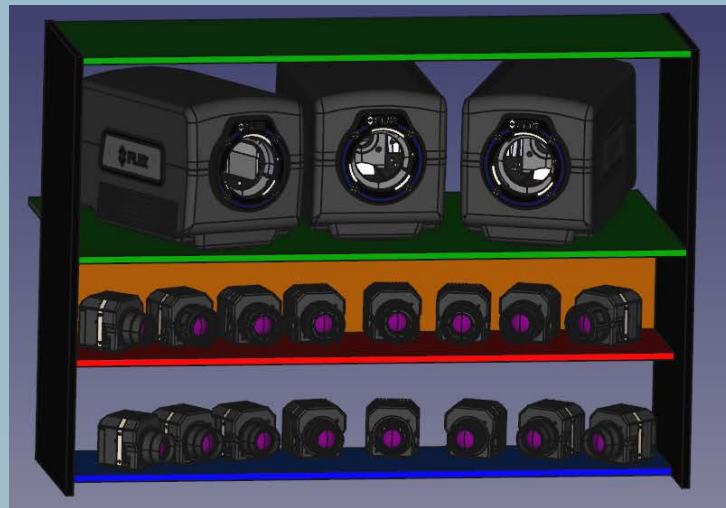


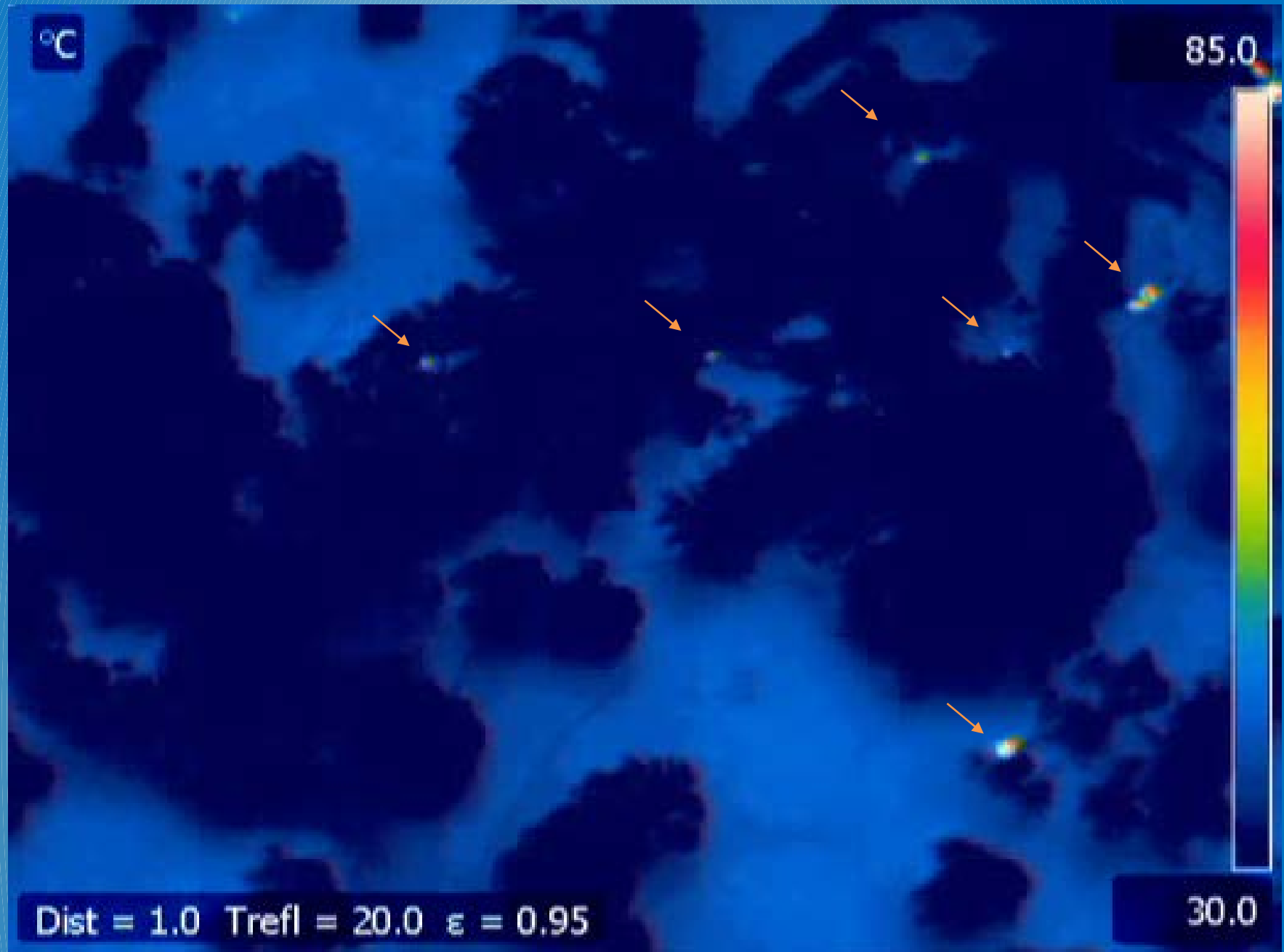
Near Real-Time, High Resolution, Day/Night Mapping and Fire Characterization

FIRE-FINDER

19 cameras 3 Infrared
Wavelengths

Wide Swath for Perimeter &
Spot Fires





SAMPLE MAPS

Real Data

Time Differential Fire Map

Current Perimeter and Activity vs. Previous Perimeter

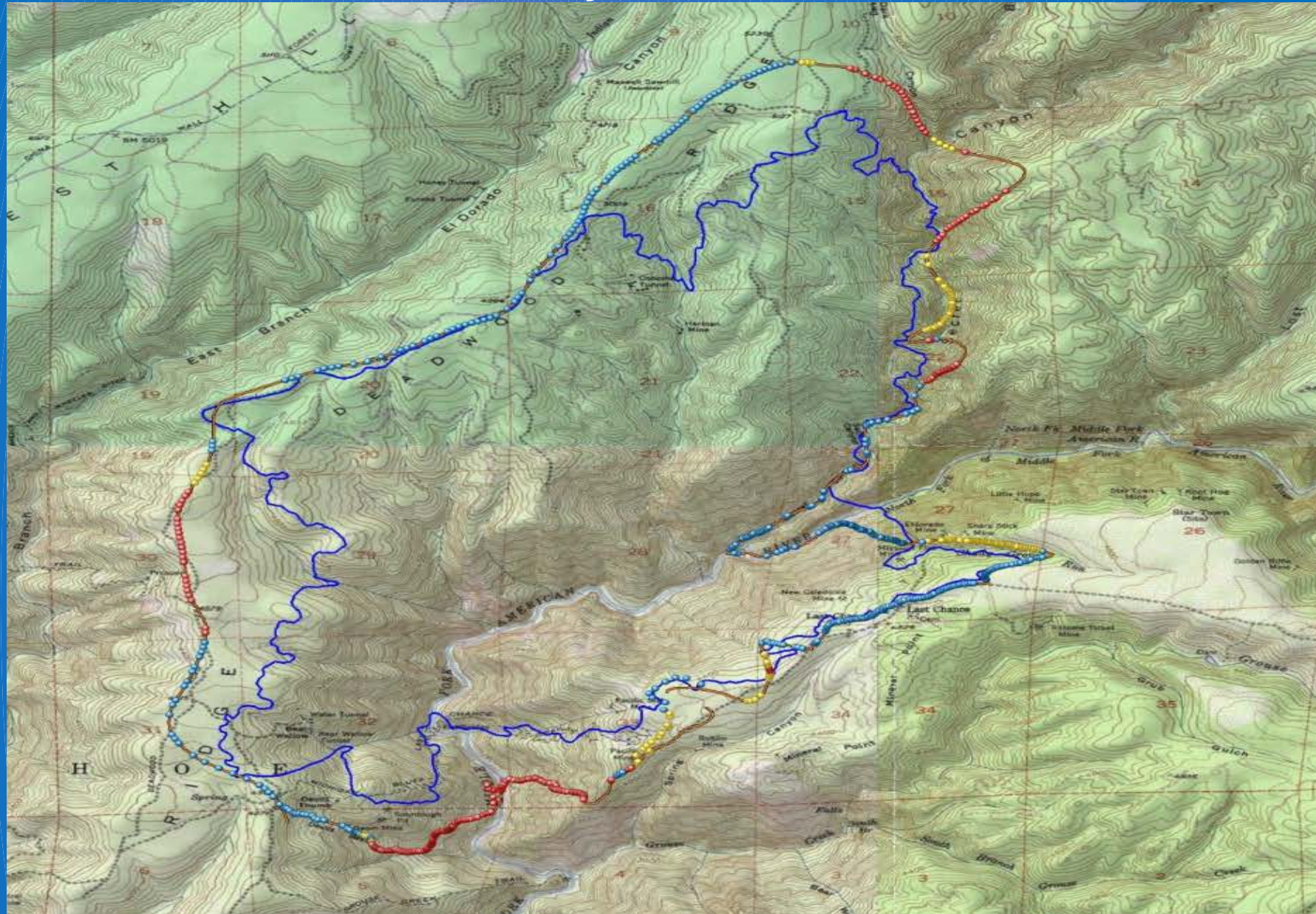
Fire Activity
North
American Incident
TNF-001562
16 Aug 2013
0830hrs

20130816_0830FireActivity

- Moving
- Creeping
- Smoldering

20130816_0830PeriPolyLine

Roads



In a few seconds you can understand:

- ✓ where the fire is moving &
- ✓ the topography where the fire is going to be hard to catch.

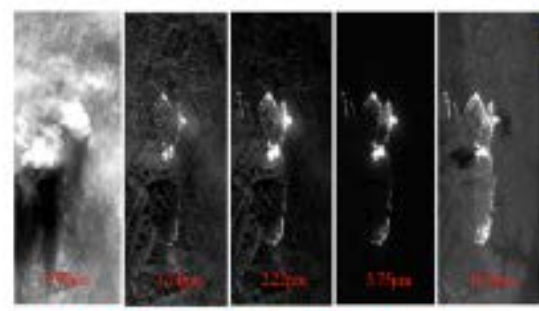
NATIONAL INFRARED OPERATIONS



Fire-Finder is Scalable

Three Wavelength Fire Analysis & Intel Dissemination Concept & Why it is Necessary

Detection, Accurate Localization & Characterization, Mop-up are Actionable Intel



Different Wavelengths (like different colors)

Pick the bands that tell what you need to know.

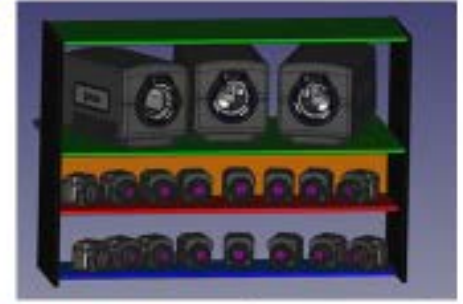
- 1.7µm - Flame Size
- 3-4µm - Energy Release
- 10µm - Smoldering



Scalable Design

Measure as wide a swath as possible at high resolution.

Fill the payload bay as appropriate for altitude.



Analyze Data On-Board in Real Time

Extract Actionable Intel:

- Perimeter Location
- Fire Front Width
- Fire Front Power
- Rate & Direction of Spread
- Put these in the context of: Wind, Slope, Exposure, Fuel and Threat to Values

Format and Disseminate the Intel as instantly understandable product.

IANSA Real Time, Two-Way, Intel Data Links



Be systematic! Mow the lawn. This is not a military, zoom-in problem. Context is everything.



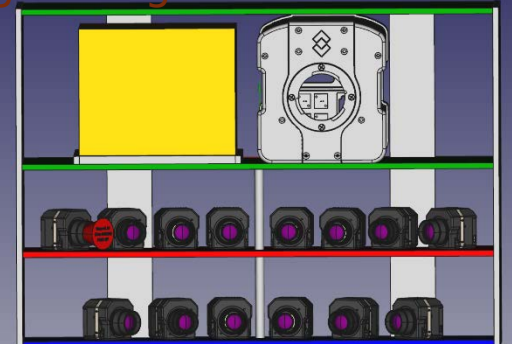
Fire-Finder Bullets

1. FireFinder can track fires in day and night. (NIROPS is night only.) This is accomplished using three well-chosen wave bands.
2. All cameras internally calibrated (NIST Traceable) and produce 14 bit data so that data is consistent comparable, and of science value.
3. Maps of
 - a. fire perimeter
 - b. total intensity (radiative energy released)
 - c. flame length (safety and tactics)
 - d. rate and direction of spread (simple linear projection updated each map cycle)
 - e. spotting frequency and spotting distance (characterizes most dangerous rates of spread) generated immediately on the aircraft (no delay waiting for IR Interpreter). NWCG GIS standard format with additions. Can be continuous, as needed.
4. Finished maps and GIS data transmitted off the aircraft in real-time. Using all available networks, the intelligence can be “pushed” to firefighters on the ground and users on the internet. Products remaining available on the cloud.
(Networks include, P-25 Radio, Satellite, Cellular, Wi-Fi, Military Grade Mesh Networks)
5. In mop-up the system finds smoldering materials as small as 3 square inches and down to 250°F.
(For comparison NIROPS detection limits are 50 square inches and 1000°F)

High Altitude, Long Duration, Solar-Electric Unmanned Vehicle

- Continuous station-keeping where threat is greatest
- Patrol large areas or track fire movement
- Real-Time, High Resolution, Day/Night Mapping and Fire Characterization
- Data transmitted direct to the Fireline

- ✓ Long-wing, solar, & engine variant of existing aircraft
- ✓ Initial Flight, 9 month after funding.
- ✓ Flight above the NAS.
- ✓ Balloon carries aircraft aloft.
- ✓ Well along path to FAA Altitude & BVLOS approval for decent (for different mission).
- ✓ Payload: a light weight variant of Fire Finder



Drone America, Phoebus

Intel is a force